

Untitled

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function [category_index predicted_vector final_delta min_difference
predicted_vector_array] = predict_best_fit_tree_N(anchor_tree, delta_tree,
new_data_item, predict_toggle, search_toggle, missing_data_vector, N)

%search_toggle must be -1,0,1,2;
%this determines whether the algorithm terminates upon the first match, best match
at first depth, or best match in the entire tree (-1,0,1), respectively.
%Search toggle of 2 switches off the possibility of a fail.
%The missing_data_vector contains the indices of the missing data items, and is
ignored unless predict_toggle = 1.
%predicted_vector will be the best match that satisfies the search_toggle criteria.
%The predicted_vector_array will contain all matches generated during the search.

[width depth] = size(anchor_tree);
new_data_vector = new_data_item{1};

predicted_vector_array = {};
index = 1; %this is the index for the predicted_vector_array

%this is to ensure we ignore any labels in the data
new_data_vector = new_data_vector(1:N);

%We initialize the return values to indicate a failure to categorize
min_difference = Inf;
final_delta = Inf;

i = 0;
break_loop_depth = 0;
break_loop_width = 0;
match = 0;

while(i < depth && break_loop_depth == 0)

    j = 0;

    while(j < width && break_loop_width == 0)

        anchor_vector = anchor_tree{width - j, depth - i};
        delta = delta_tree{width - j, depth - i};

        if(isempty(anchor_vector) == 0)

            if(predict_toggle == 1)

                new_data_vector(missing_data_vector(:)) =
anchor_vector(missing_data_vector(:));

            endif

        endif

    end

endwhile
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temp_anchor = anchor_vector(1:N);

difference = norm(new_data_vector - temp_anchor);

%Either we have a match, or we've reached the top of the tree, or we've
disabled fails
if(difference <= delta || anchor_vector(3) == Inf || search_toggle == 2)

    %if true, then we have a match
    if(difference < min_difference)

        match = 1;
        predicted_vector = new_data_vector;
        category_index = [(width - j) (depth - i)];
        final_delta = delta;
        min_difference = difference;

        %if true, then we terminate upon first match
        if(search_toggle == -1)

            break_loop_depth = 1;
            break_loop_width = 1;

        %if true, then we terminate at the end of the current depth
        elseif(search_toggle == 0)

            break_loop_depth = 1;

        %otherwise, search_toggle is 1 or 2, so we search the entire tree

    endif

    %if true, then we've reached the top of the tree with no match
    elseif(anchor_vector(3) == Inf && match == 0)

        predicted_vector = anchor_vector;
        category_index = [(width - j) (depth - i)];

    endif

    %In all cases except where we've reached the top of the tree, we have a
possible match
    if(anchor_vector(3) != Inf)

        predicted_vector_array{index} = new_data_vector;
        index = index + 1;
```

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        endif
    endif
endif
    j = j + 1;
endwhile
    i = i + 1;
endwhile
endfunction
```